

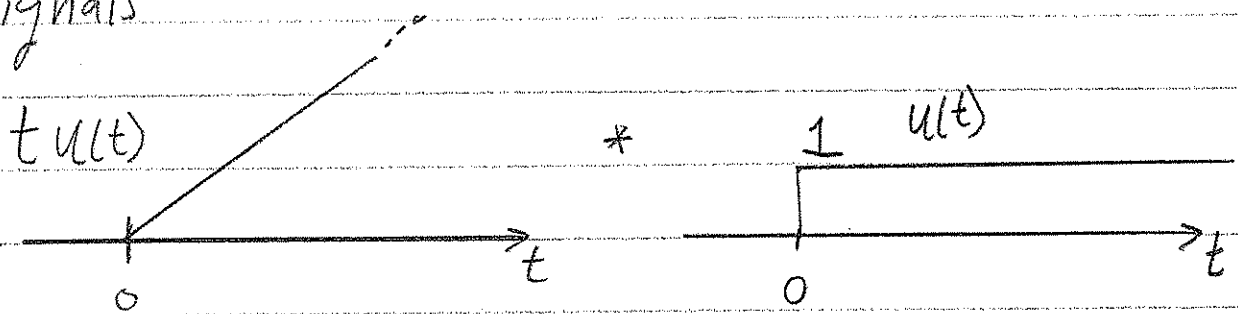
EE 3054 - TEST 2 - FALL 2008

①  $f(t) = u(t)$ ,  $g(t) = 3e^{-2t}u(t)$

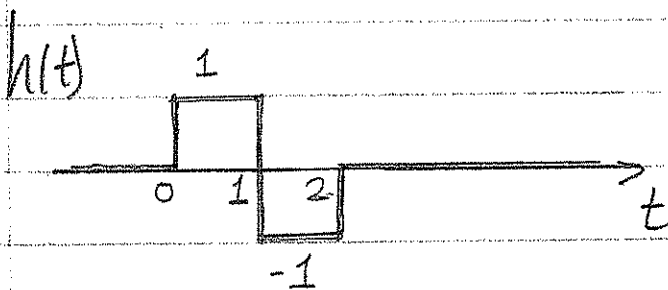
Find  $x(t) = f(t) * g(t)$ . (convolution.)

Also sketch  $x(t)$ .

② Find the convolution of the following two signals



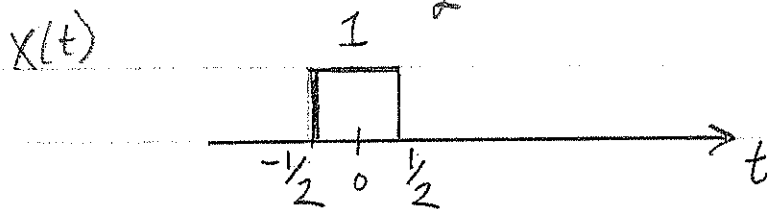
③ An LTI system has the impulse response shown:



(a) Accurately sketch the step response of the system.

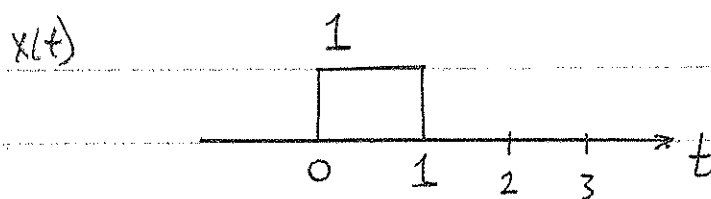
(b) Find the transfer function  $H(s)$ .

- ④ a) Find the Fourier transform  $X^f(\omega)$  of  $x(t)$ ,  
- write  $X^f(\omega)$  using the sinc function.



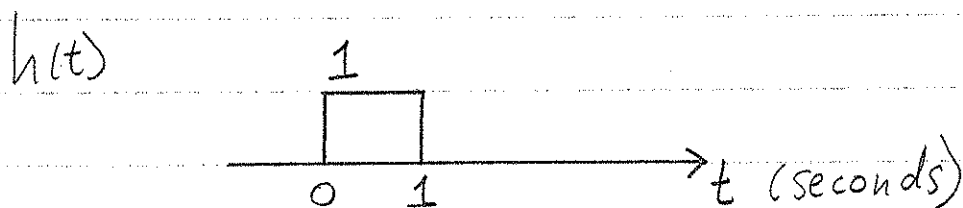
- b) sketch  $X^f(\omega)$ , indicate the nulls of  $X^f(\omega)$ .

- ⑤ a) Find  $X^f(\omega)$  for  $x(t)$ ,



- b) sketch  $|X^f(\omega)|$ , indicate the nulls of  $|X^f(\omega)|$ ,  
indicate the nulls of  $|X^f(\omega)|$ .

- ⑥ If an LTI system has the impulse response



then what frequencies are completely stopped by the system? Express the frequencies in Herz.

hint: use (#5)

⑦ An <sup>causal</sup> LTI system is described by the diff. eq.

$$y''(t) + 5y'(t) + 4y(t) = 2x'(t) + x(t).$$

a) Find the impulse response,  $h(t)$ .

b) Sketch the pole/zero diagram.

⑧ The impulse response of an LTI system is

$$h(t) = 2u(t) + 3e^{-2t}u(t)$$

a) Find the differential equation for the system.

b) sketch the pole/zero diagram.

c) classify the system as stable/unstable.

⑨  $x(t) = 2\cos(\pi t) + \cos(1.5\pi t)$

a) Find and sketch the Fourier Transform  $X^f(\omega)$ .

b) Find the Fourier series coefficients  $c(k)$  and the fundamental frequency  $\omega_0$ ,

c) Also, sketch the line spectrum of  $x(t)$ .

⑩ Find and sketch the Fourier transform of

$$x(t) = \cos(3\pi t) \cdot \cos(4\pi t).$$

## MATLAB PART

M1) An EE 3054 student uses the following MATLAB code to implement a discrete-time system.

$$b = [4 \ 2 \ 1];$$

$$a = [3 \ 5];$$

$$y = \text{filter}(b, a, x);$$

- a) what is the transfer function  $H(z)$  of the system?  
b) " " " difference equation " " " ?

M2) What is the result of the commands:

a)  $\text{roots}([1 \ 1 \ -6])$

b)  $\text{poly}([2 \ 3 \ 1])$

M3) Write MATLAB commands to produce a 10 second cosine signal of frequency 3.5 Hz, the sampling interval for your MATLAB command should be 0.1 seconds.

selected Laplace transform pairs

$x(t)$	$X(s)$	ROC
$x(t)$	$\int x(t)e^{-st} dt$ (def.)	
$\delta(t)$	1	all $s$
$u(t)$	$\frac{1}{s}$	$\text{Re}(s) > 0$
$e^{-\alpha t} u(t)$	$\frac{1}{s + \alpha}$	$\text{Re}(s) > -\alpha$
$\cos(\omega_0 t) u(t)$	$\frac{s}{s^2 + \omega_0^2}$	$\text{Re}(s) > 0$
$\sin(\omega_0 t) u(t)$	$\frac{\omega_0}{s^2 + \omega_0^2}$	$\text{Re}(s) > 0$
$e^{-\alpha t} \cos(\omega_0 t) u(t)$	$\frac{s + \alpha}{(s + \alpha)^2 + \omega_0^2}$	$\text{Re}(s) > -\alpha$
$e^{-\alpha t} \sin(\omega_0 t) u(t)$	$\frac{\omega_0}{(s + \alpha)^2 + \omega_0^2}$	$\text{Re}(s) > -\alpha$

Note:  $\alpha$  is assumed real.

Laplace transform properties

$x(t)$	$X(s)$
$a x(t) + b g(t)$	$a X(s) + b G(s)$
$x(t) * g(t)$	$X(s) G(s)$
$\frac{dx(t)}{dt}$	$s X(s)$
$x(t - t_0)$	$e^{-s t_0} X(s)$

useful formulas

name	formula
Euler's formula	$e^{j\theta} = \cos(\theta) + j \sin(\theta)$
... for cosine	$\cos(\theta) = \frac{e^{j\theta} + e^{-j\theta}}{2}$
... for sine	$\sin(\theta) = \frac{e^{j\theta} - e^{-j\theta}}{2j}$
sinc function	$\text{sinc}(\theta) := \frac{\sin(\pi \theta)}{\pi \theta}$

formulas for continuous-time LTI signals and systems

name	formula
area under impulse	$\int \delta(t) dt = 1$
multiplication by impulse	$f(t) \delta(t) = f(0) \delta(t)$
... by shifted impulse	$f(t) \delta(t - t_0) = f(t_0) \delta(t - t_0)$
convolution	$f(t) * g(t) = \int f(\tau) g(t - \tau) d\tau$
... with an impulse	$f(t) * \delta(t) = f(t)$
... with a shifted impulse	$f(t) * \delta(t - t_0) = f(t - t_0)$
transfer function	$H(s) = \int h(t) e^{-st} dt$
frequency response	$H^f(\omega) = \int h(t) e^{-j\omega t} dt$
... their connection	$H^f(\omega) = H(j\omega)$ provided $j\omega$ -axis $\subset$ ROC

selected Fourier transform pairs

$x(t)$	$X^f(\omega)$
$x(t)$	$\int x(t) e^{-j\omega t} dt$ (def.)
$\frac{1}{2\pi} \int X^f(\omega) e^{j\omega t} d\omega$	$X^f(\omega)$
$\delta(t)$	1
1	$2\pi \delta(\omega)$
$u(t)$	$\pi \delta(\omega) + \frac{1}{j\omega}$
$e^{j\omega_0 t}$	$2\pi \delta(\omega - \omega_0)$
$\cos(\omega_0 t)$	$\pi \delta(\omega + \omega_0) + \pi \delta(\omega - \omega_0)$
$\sin(\omega_0 t)$	$j\pi \delta(\omega + \omega_0) - j\pi \delta(\omega - \omega_0)$
$\frac{\omega_0}{\pi} \text{sinc}\left(\frac{\omega_0 t}{\pi}\right)$	ideal LPF cut-off frequency $\omega_0$
symmetric pulse width $T$ , height 1	$\frac{2}{\omega} \sin\left(\frac{T}{2}\omega\right)$
impulse train period $T$ , height 1	impulse train period, height $\omega_0 = \frac{2\pi}{T}$

Fourier transform properties

$x(t)$	$X^f(\omega)$
$a x(t) + b g(t)$	$a X^f(\omega) + b G^f(\omega)$
$x(at)$	$\frac{1}{ a } X\left(\frac{\omega}{a}\right)$
$x(t) * g(t)$	$X^f(\omega) G^f(\omega)$
$x(t) g(t)$	$\frac{1}{2\pi} X^f(\omega) * G^f(\omega)$
$x(t - t_0)$	$e^{-j\omega t_0} X(\omega)$
$x(t) e^{j\omega_0 t}$	$X(\omega - \omega_0)$
$x(t) \cos(\omega_0 t)$	$0.5 X(\omega + \omega_0) + 0.5 X(\omega - \omega_0)$
$x(t) \sin(\omega_0 t)$	$j 0.5 X(\omega + \omega_0) - j 0.5 X(\omega - \omega_0)$
$\frac{dx(t)}{dt}$	$j\omega X^f(\omega)$