

① A causal discrete-time LTI system is implemented using the difference equation

$$y(n] = x(n] + x(n-1] + 0.5y(n-1]$$

a) sketch the pole-zero diagram

b) find the dc gain

c) find the value of the freq. resp. at frequency $\omega = \pi$

d) find $|H^f(0.5\pi)|$

e) Based on (a-d), roughly sketch the freq. resp. magnitude $|H^f(\omega)|$. Indicate its value at $\omega = 0, 0.5\pi$, and π .

f) what is the output produced by the input signal $x(n] = 2^n$?

② Design a simple real causal discrete-time LTI system that

a) annihilates the signal $\cos(\frac{2}{3}\pi n]$

b) has a dc gain of unity

c) annihilates the signal $(-1)^n$.

For the system you design:

a) find the impulse response - sketch $h(n]$.

b) find the difference equation

c) find simplified formulas for $|H^f(\omega)|$ [OPTIONAL - extra credit 1 pt]

d) show the pole-zero diagram

e) roughly sketch the freq. resp. magnitude, $|H^f(\omega)|$, based on zeros of system.

③ Matching problem (next page).

The impulse responses, frequency responses, and pole-zero diagrams of 4 causal discrete-time LTI systems are shown. But the diagrams are out of order. Match each diagram by filling out the following table.

$h(n)$	$ H^f(\omega) $	P-Z
1		
2		
3		
4		

